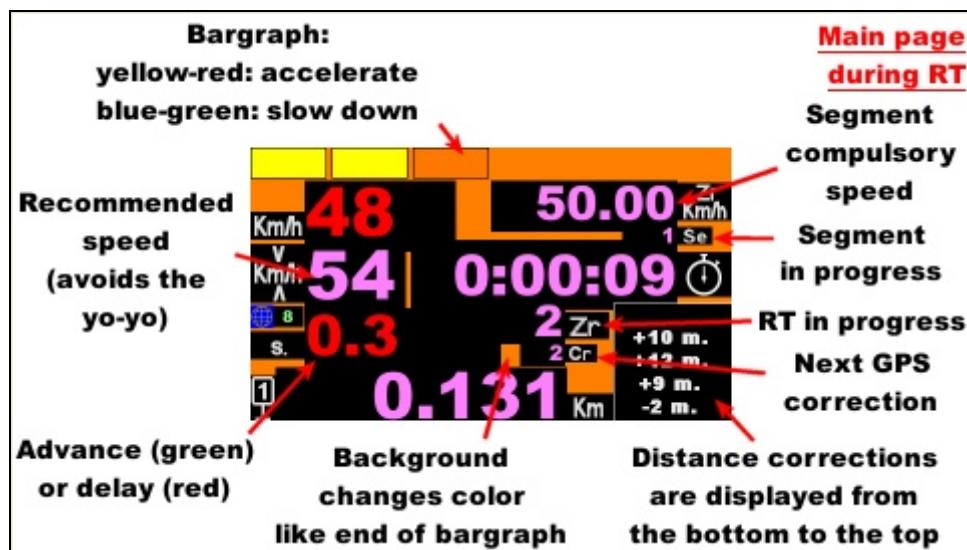
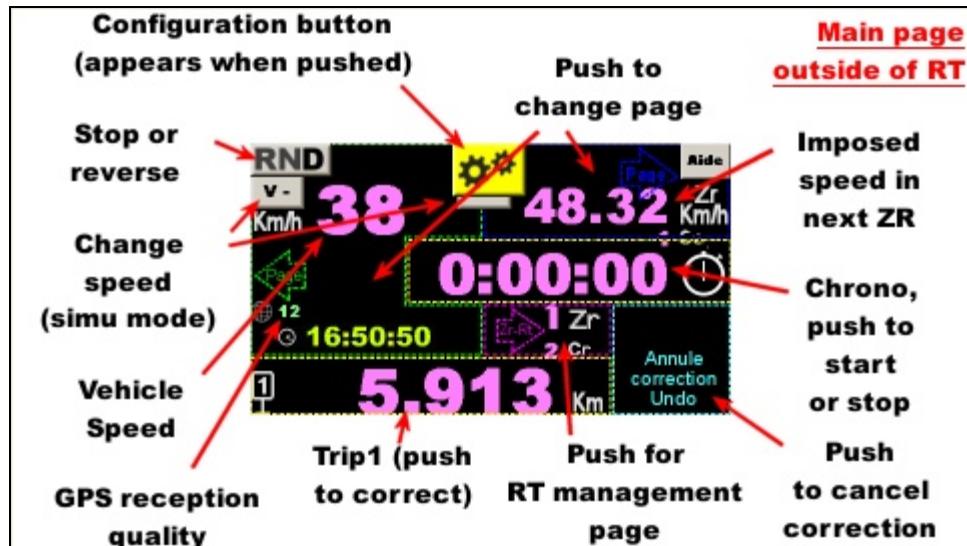


## Help pages

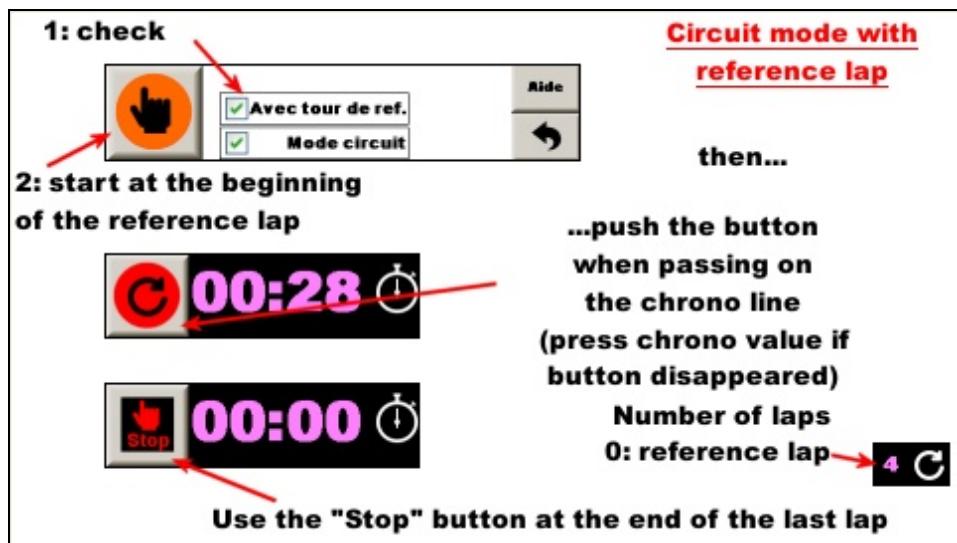
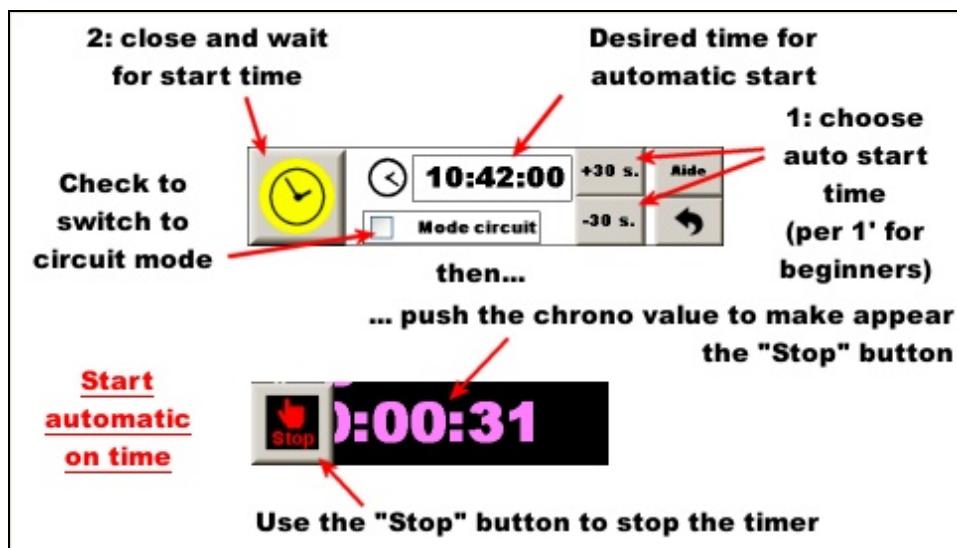
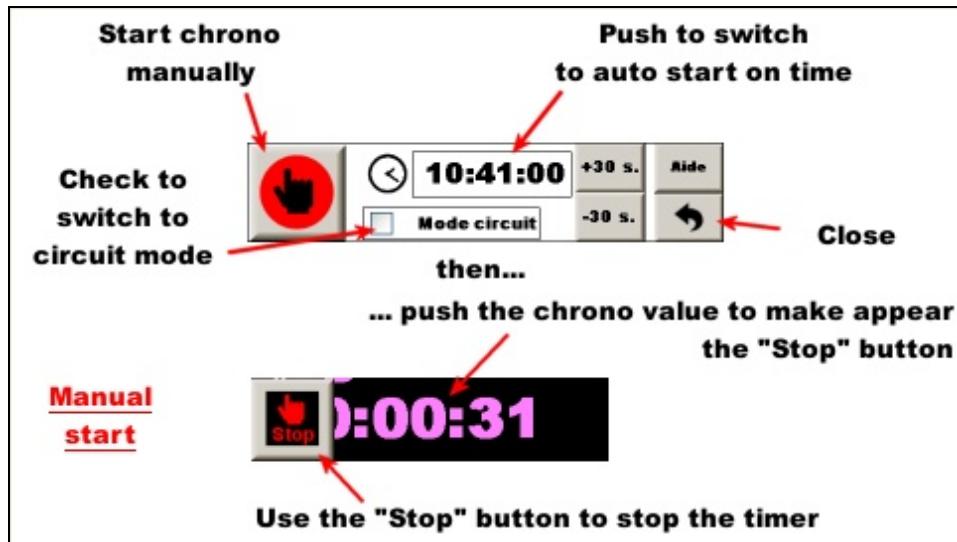
### 1 « regularity » page (main page)

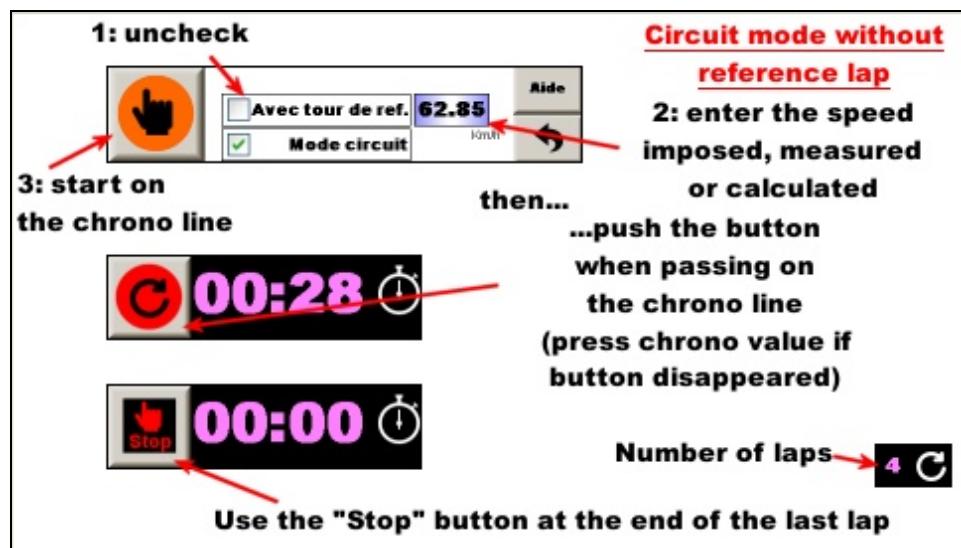


### 2 Trip modification

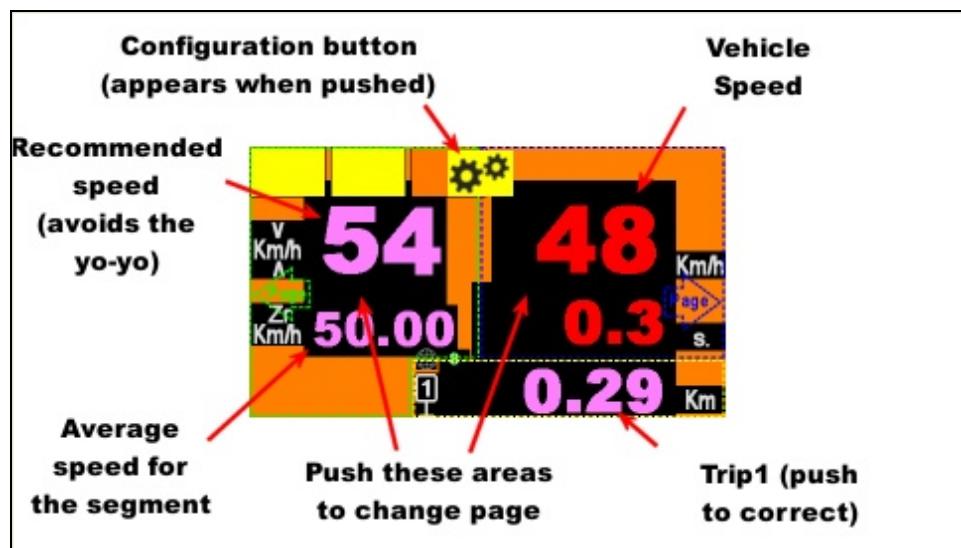
Numbers for direct modification			Frozen distance (black) or modified (blue)		
Delete	7	8	9	122.896	-0.104
Trip in modification (continues to run)	4	5	6	+ 1	+ 10
	1	2	3	- 1	- 10
	0	.	<-	Apply gap	New value
				123.000	Km Help ⌂
Apply the gap (correction of the frozen value, not in beginner mode)					
Write the new prepared value (when pushed)					

### 3 Stopwatch

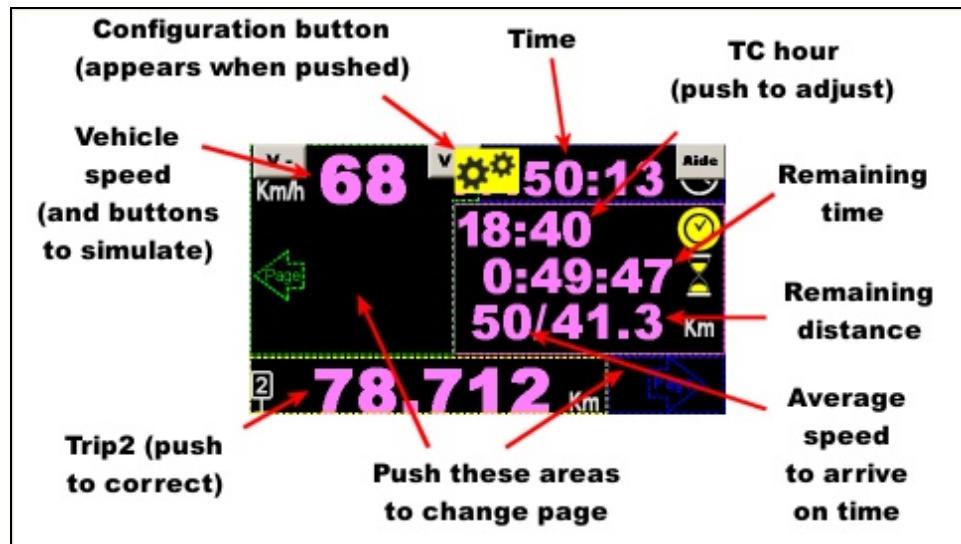




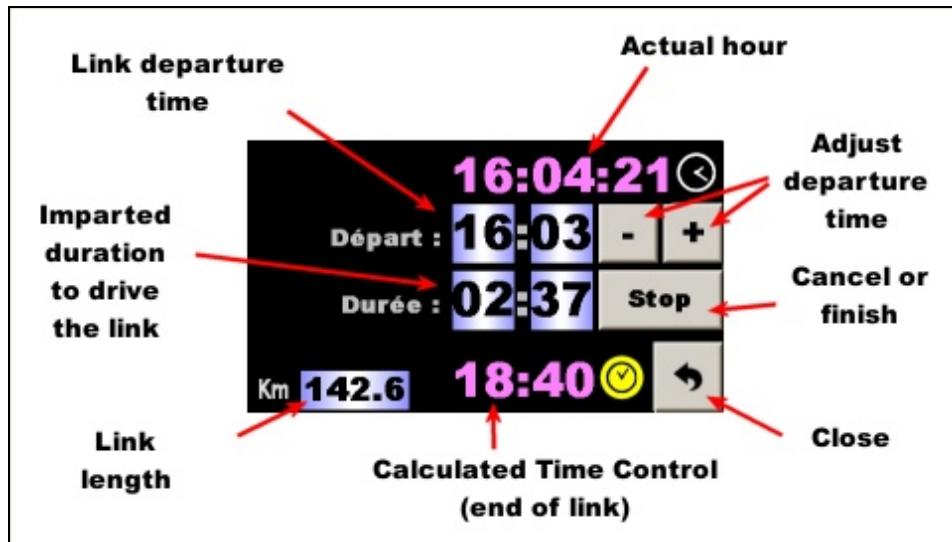
#### 4 « pilot » page



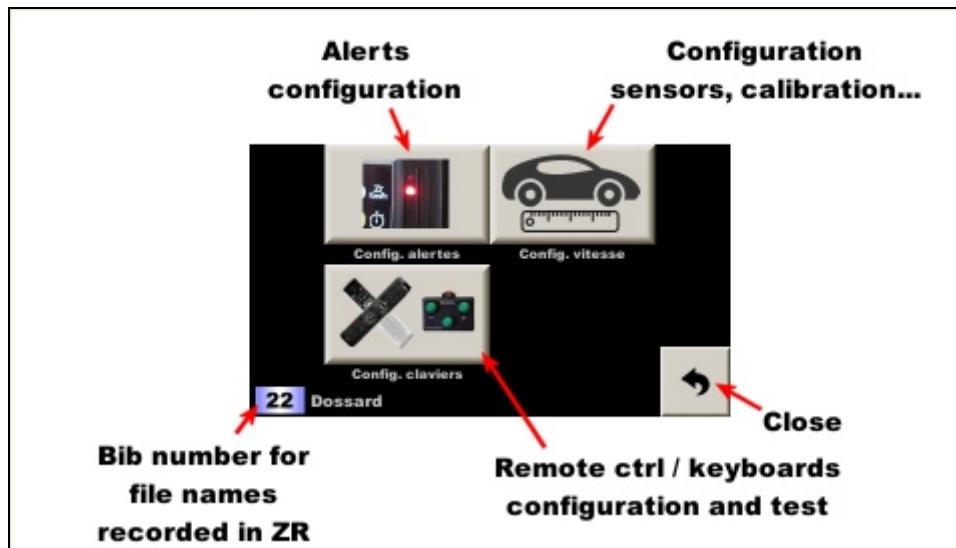
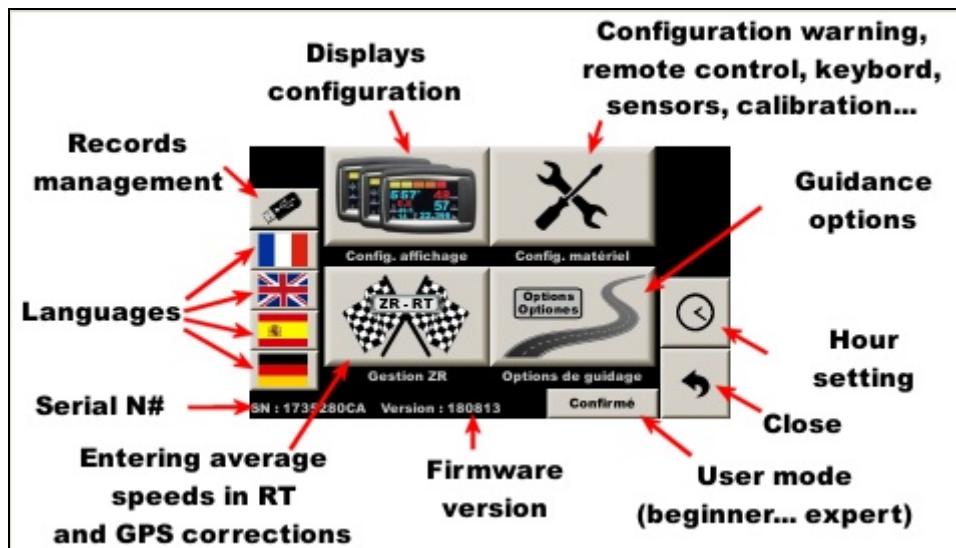
#### 5 « link » page

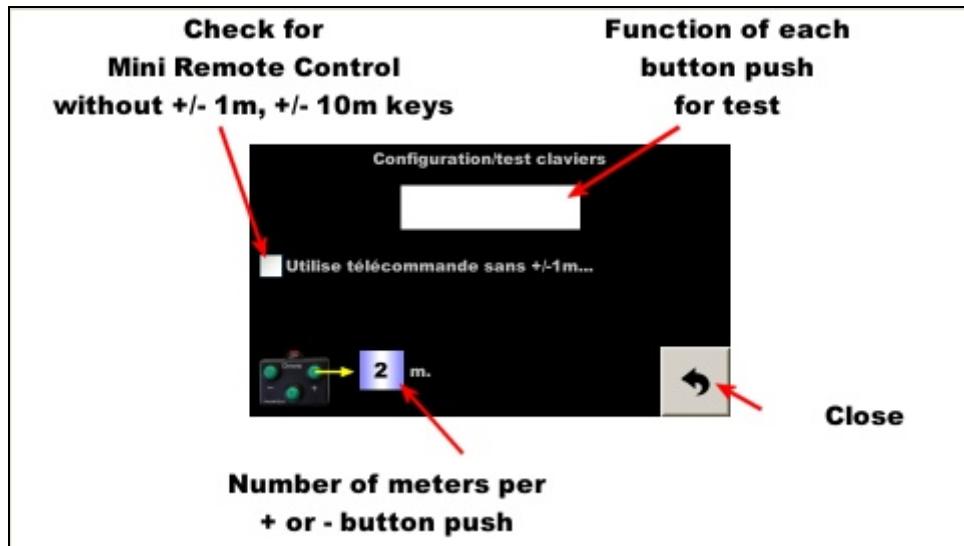


set ideal TC hour:

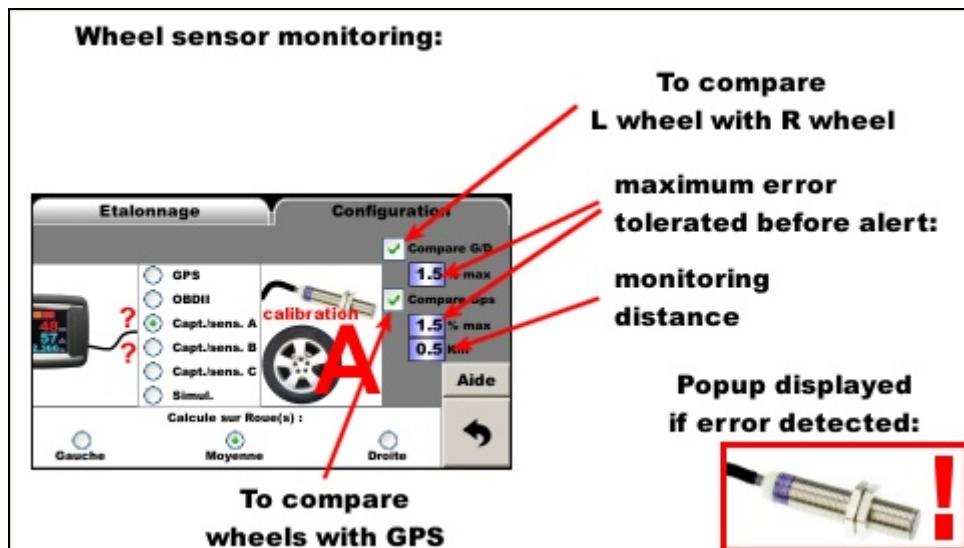
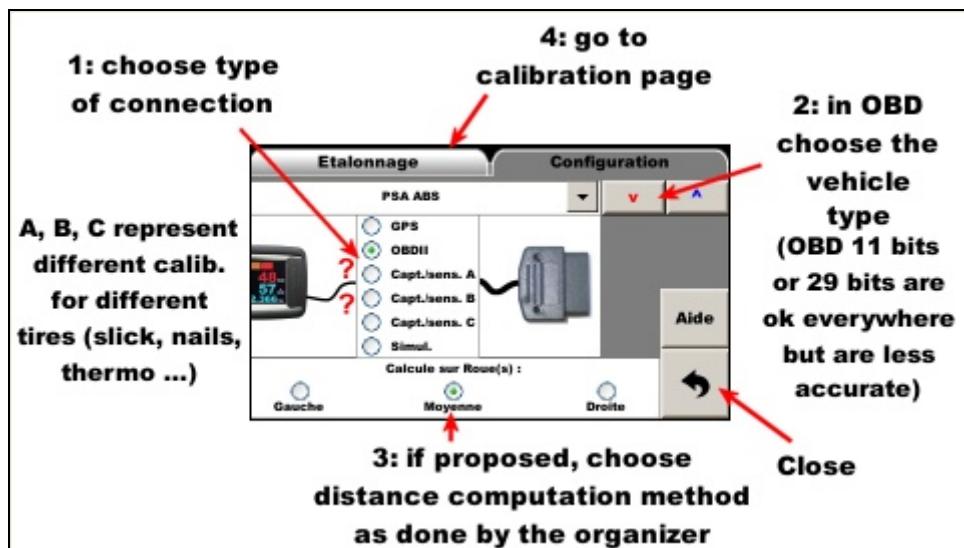


## 6 Configuration





## 6.1 Sensors configuration, calibration...



**Tires centrifugal swelling compensation (expert mode)**

**Display calibration history**

**Edit calibration on the fly or bt +/- 1m (except beginner mode)**

**Type here the calibration value, if it is already known**

**1: choice of Trip1 or 2 or a distance freely copied (compute without drive)**

**2: Reset at calibration zone start**

**3: drive the zone or type in the distance**

**4: Type calibration distance given by the organizer**

**5: compute**

**Calibrate the GPS at same time**

**Close**

**In "sensor" mode, for GPS based calibration (fast but not very precise):**

**Connection configuration (sensors, OBD, GPS...)**

**1: click GPS mode**

**2: drive in straight line**

**3: compute while driving**

**Check each sensor pulses (if available)**

## 6.2 Distances/speed management during RT

**RT are recorded in files**

**RT choice**

**One line for each speed (segment)**

**Km of beginning and end of segment**

**0.000**

**Theoretical chrono at the end of segment**

**MultiSpeeds mode**

**Scroll the lines**

**Close**

**Speed on the segment (km/h)**

**Trip1**

**'Gravel crew' data page**

**New RT**

**GPS corrections page**

**Save RT**

**Import from USB export to USB**

**Delete ALL data of ALL RT**

Ind	Début	Fin	Vitesse	Timing		Aide
1	0.000	3.658	48.32	4:32.5		
2	3.658	5.215	46.36	6:33.4		
3	5.215	8.698	49.99	10:44.2		
4	8.698	12.375	47.02	15:25.7		
				Nbr : 4		
				Km		

**0.000**

## 6.3 Automatic corrections by GPS

**Points are recorded in the file at each addition**

**Configuration**

**New file**

**Adjust distances**

**Distance since last point**

**Delete the last point**

**Supprime**

**Ajoute inter**

**Ajoute absolu**

**comment**

**0.227**

**40.012 Km**

**Latitude**

**Longitude**

**Nbr : 181**

**Commentaire**

**Auto Km**

**0.200**

**28**

**Duplicate (if multiple passages in the race)**

**Total number of points**

**Scroll the lines**

**GPS reception quality**

Ind	Km	Latitude	Longitude			
178	35.134	44.865795	5.582873			
179	39.488	44.866943	5.586785			
180	39.785	44.866596	5.590035			

**GPS points**  
manual entry

**1: type a comment  
(optional)**

**2: add a point after  
tight turn, or ...  
(limited distance correction)**

**... add a point without  
correction limitation  
(not after tight turn)**

**GPS points**  
automatic entry  
(road without tight turn)

**1: type distance  
between two points**

**It remains possible to  
enter a point manually  
between 2 automatic points**

**2: check**

**Add a distance  
to all points**

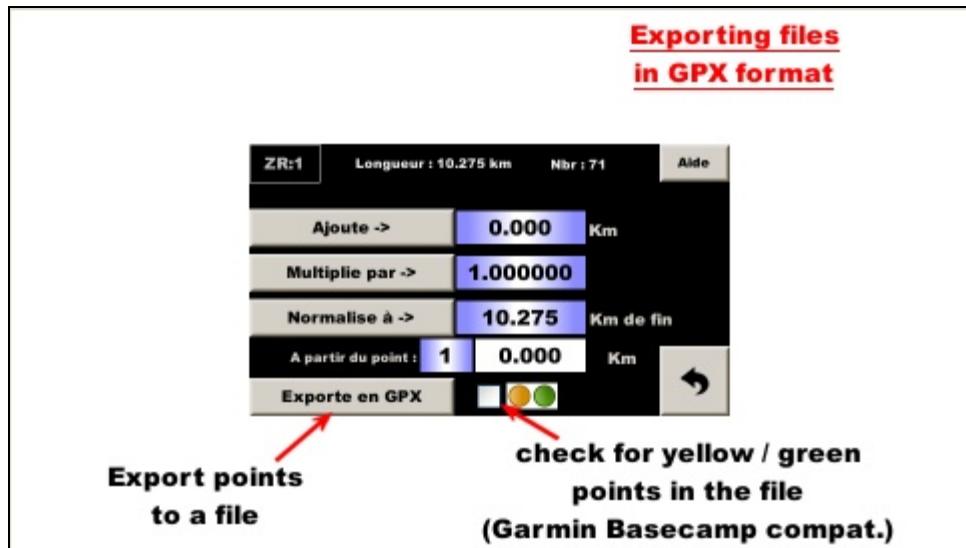
**Multiply all  
points by  
a coefficient**

**3 : push  
button**

**Match to a  
road-book box:**

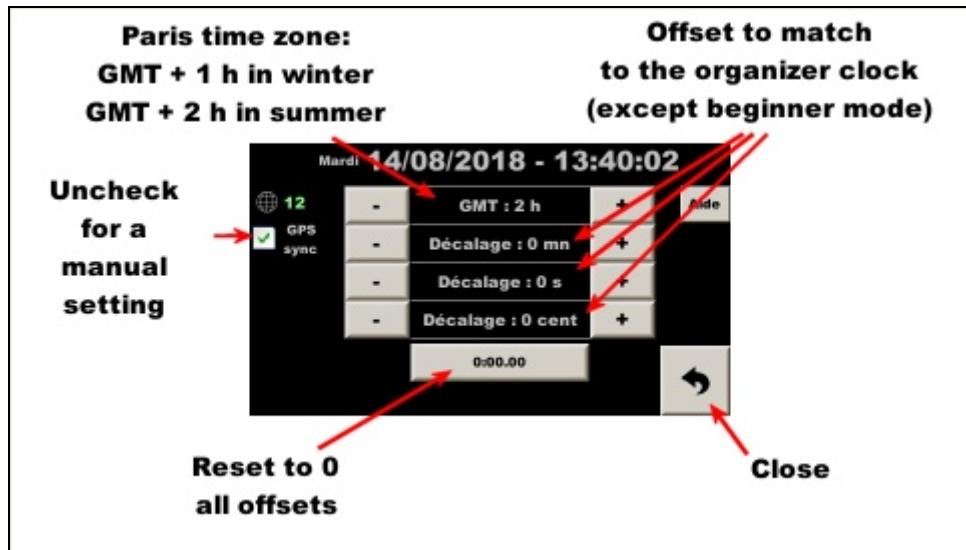
**1: type  
distance  
exact of  
the box**

**2: check that it corresponds  
to the previous correct point  
(not in beginner mode)**

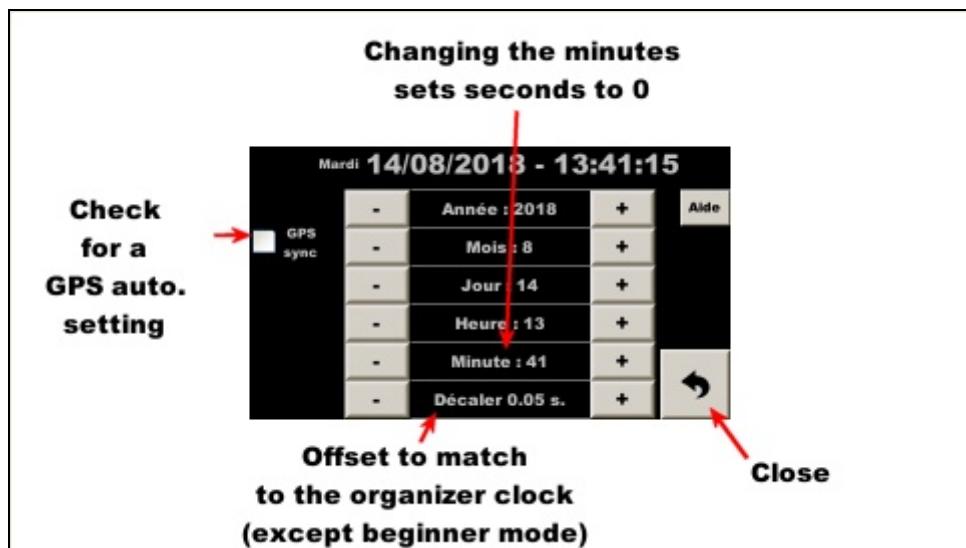


## 6.4 Date / hour setting

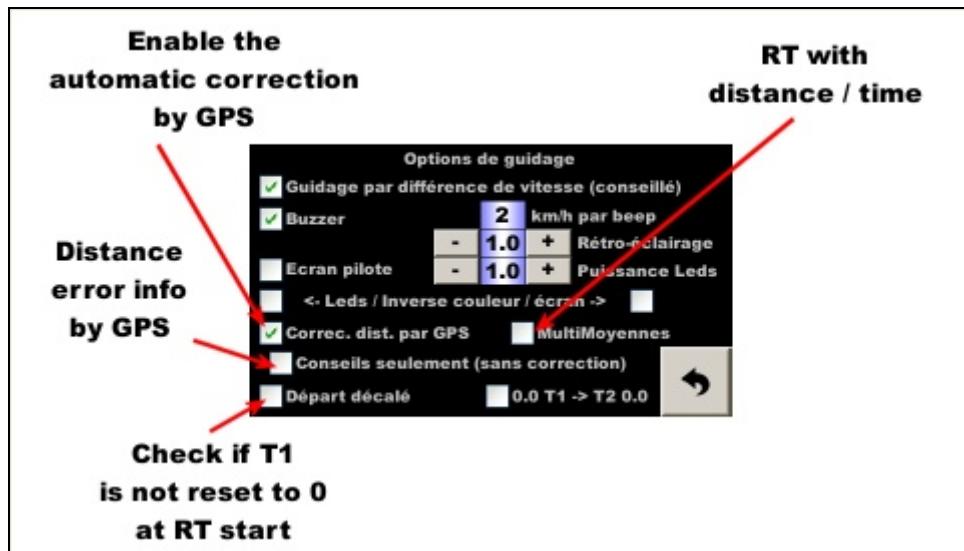
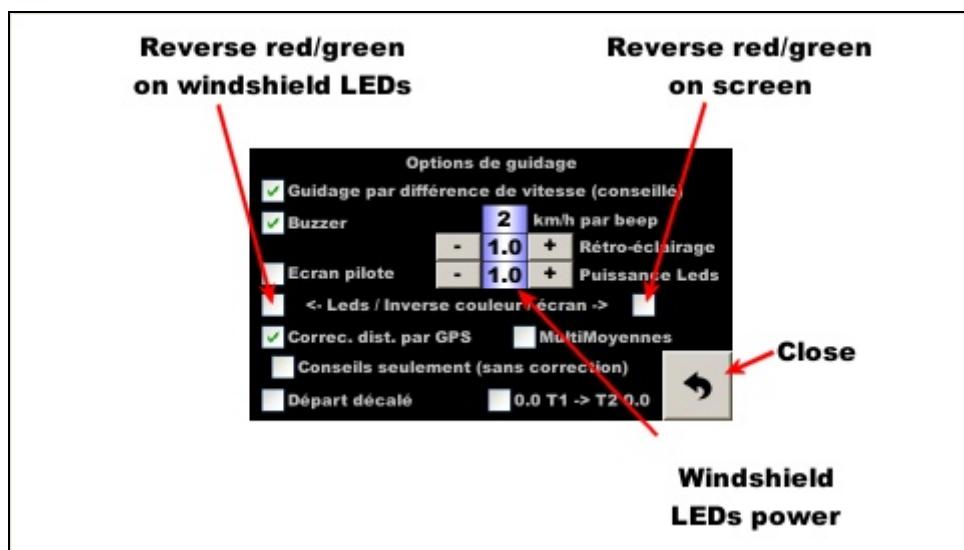
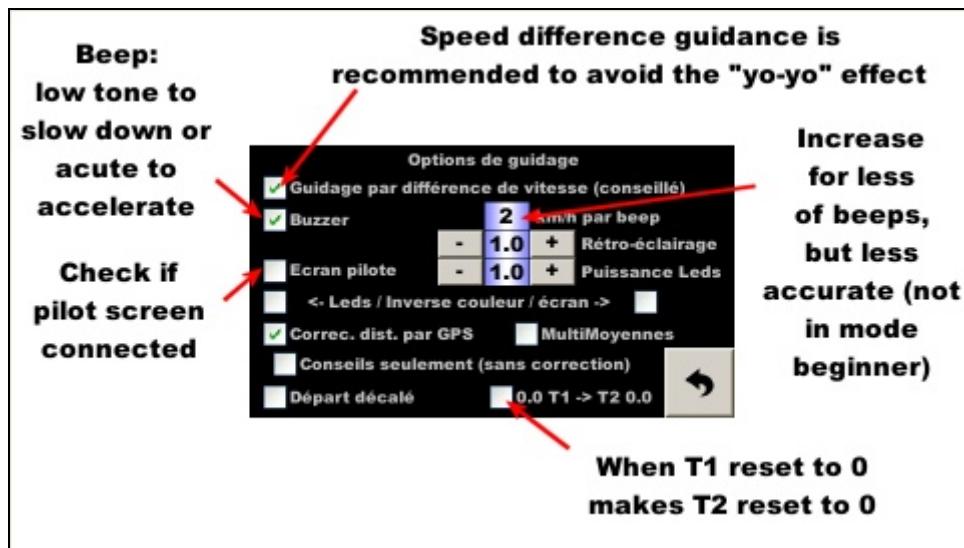
with GPS auto-synchronisation:



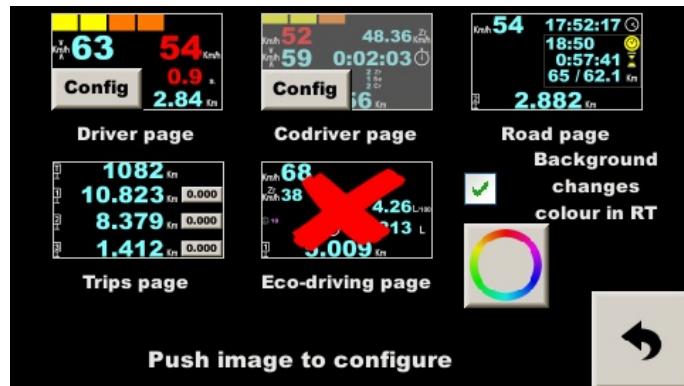
manual setting:



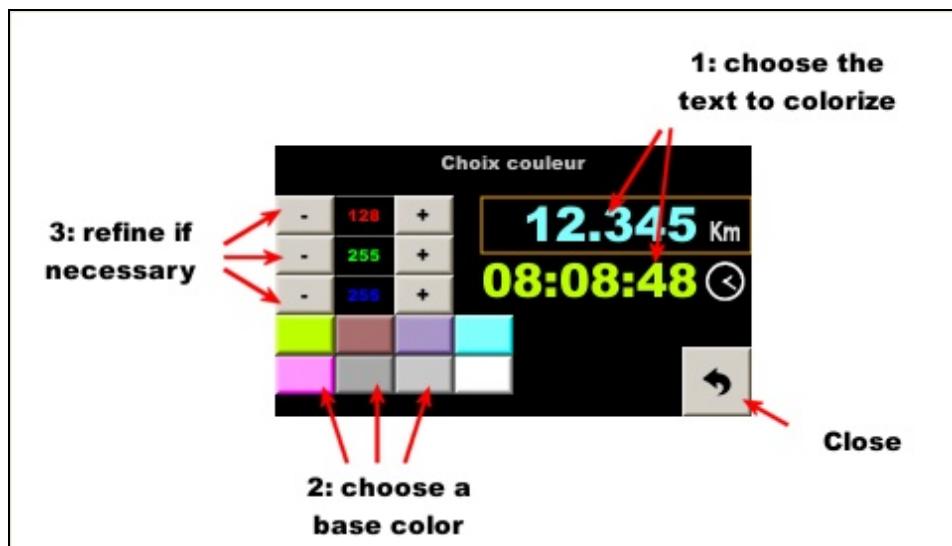
## 6.5 Guidance options



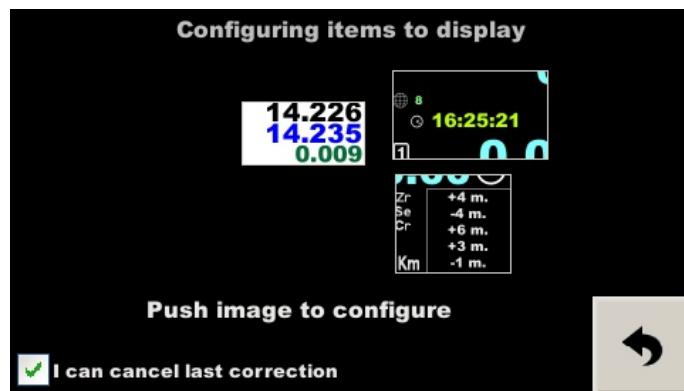
## 6.6 Display configuration



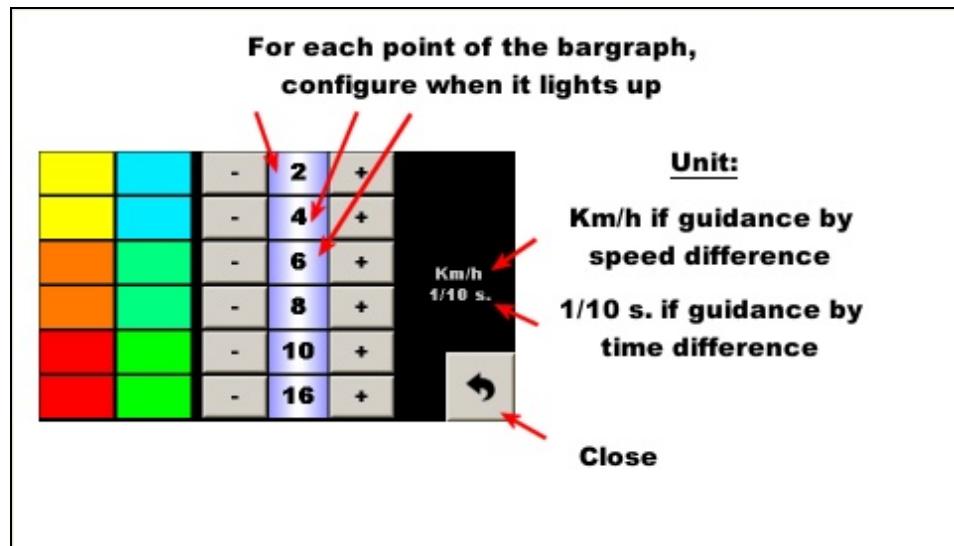
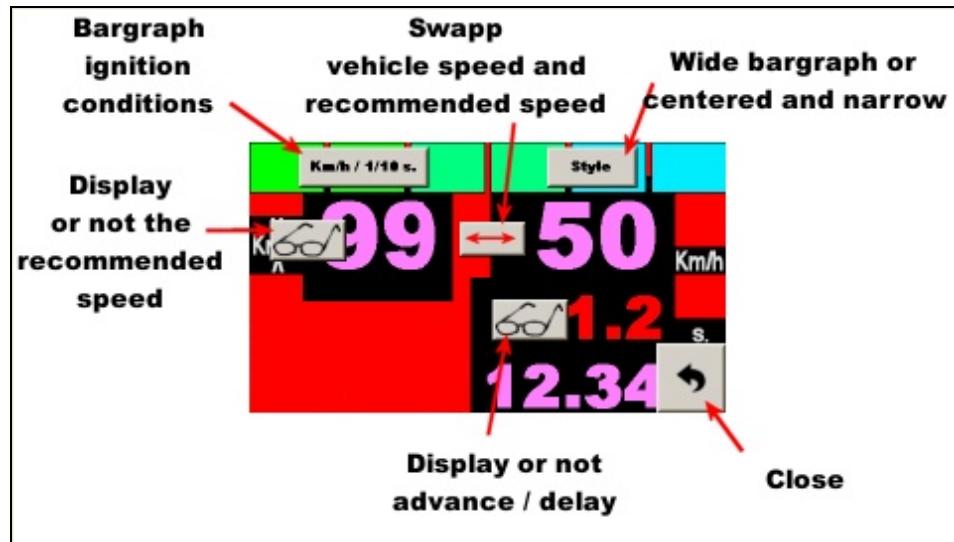
Press the color palette button to set the text color:



« codriver » page, remove some information pressing on images:



« pilot » page (configures also RP400 if connected):



## 6.7 Files recording

